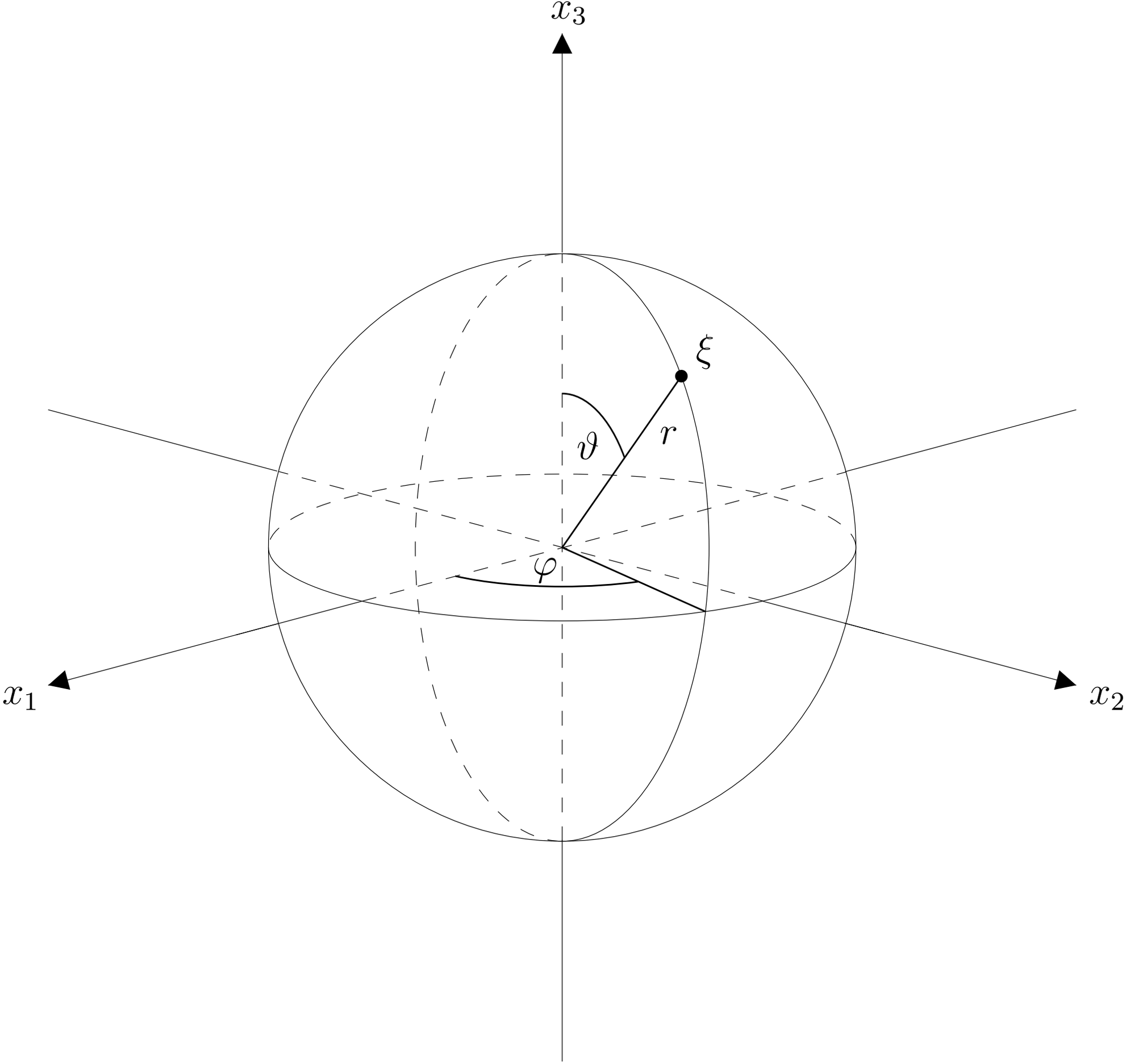
x_3
ξ
ϑ
r
φ
x_1
x_2